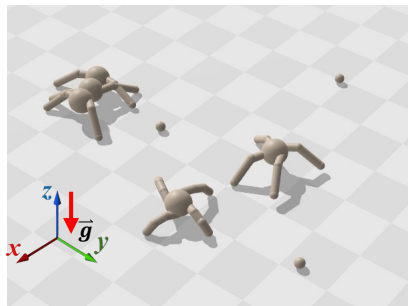


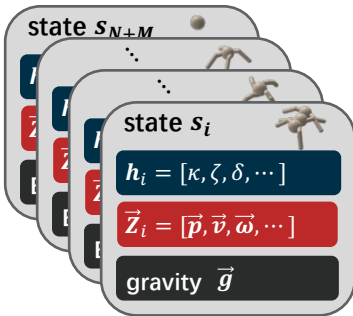
SHNN

MeBen: Team Reach

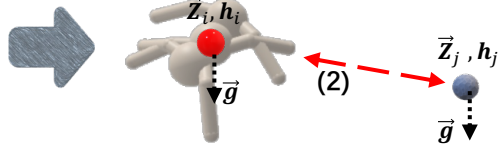


observations

(1) Input Processing

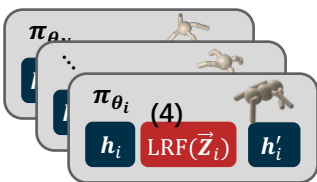


(3) Local Entity-level
Subequivariant
Message Passing



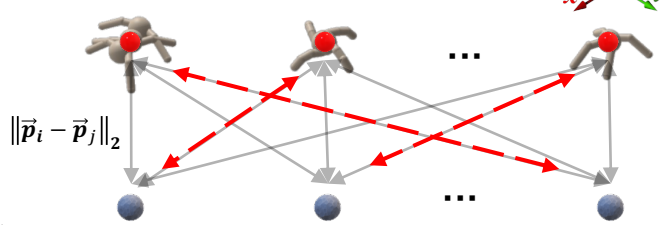
$$\{(\vec{z}'_i, h'_i)\}_{i=1}^{N+M} = \varphi_0 \left(\{(\vec{z}_i, h_i)\}_{i=1}^{N+M}, \mathcal{E} \right)$$

(5) Body-level control



actions

\longleftrightarrow : (2) Task Assignment



$LRF(\vec{z}_i)$: (4) Local Reference Frame Transform

